

CONTROL FUNCTION AND RELATED METHODS

Jeff Wooldridge
Michigan State University
LABOUR Lectures, EIEF
October 18-19, 2011

1. Linear-in-Parameters Models: IV versus Control Functions
2. Correlated Random Coefficient Models
3. Nonlinear Models
4. Semiparametric and Nonparametric Approaches
5. Methods for Panel Data

1. Linear-in-Parameters Models: IV versus Control Functions

- Most models that are linear are estimated using standard IV methods: two stage least squares (2SLS) or generalized method of moments (GMM).
- An alternative, the control function (CF) approach, relies on the same kinds of identification conditions. But even in models linear in parameters it can lead to different estimators.

- Let y_1 be the response variable, y_2 the endogenous explanatory variable (EEV), and \mathbf{z} the $1 \times L$ vector of exogenous variables (with $z_1 = 1$):

$$y_1 = \mathbf{z}_1 \boldsymbol{\delta}_1 + \alpha_1 y_2 + u_1, \quad (1)$$

where \mathbf{z}_1 is a $1 \times L_1$ strict subvector of \mathbf{z} .

- First consider the exogeneity assumption

$$E(\mathbf{z}'u_1) = \mathbf{0}. \quad (2)$$

Reduced form for y_2 :

$$y_2 = \mathbf{z}\boldsymbol{\pi}_2 + v_2, \quad E(\mathbf{z}'v_2) = \mathbf{0} \quad (3)$$

where $\boldsymbol{\pi}_2$ is $L \times 1$. Write the linear projection of u_1 on v_2 , in error form, as

$$u_1 = \rho_1 v_2 + e_1, \quad (4)$$

where $\rho_1 = E(v_2 u_1)/E(v_2^2)$ is the population regression coefficient. By construction, $E(v_2 e_1) = 0$ and $E(\mathbf{z}'e_1) = \mathbf{0}$.

Plug (4) into (1):

$$y_1 = \mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1y_2 + \rho_1v_2 + e_1, \quad (5)$$

where v_2 is an explanatory variable in the equation. The new error, e_1 , is uncorrelated with y_2 as well as with v_2 and \mathbf{z} .

- Suggests a two-step estimation procedure:

- (i) Regress y_2 on \mathbf{z} and obtain the reduced form residuals, \hat{v}_2 .

- (ii) Regress

$$y_1 \text{ on } \mathbf{z}_1, y_2, \text{ and } \hat{v}_2. \tag{6}$$

The implicit error in (6) is $e_{i1} + \rho_1 \mathbf{z}_i (\hat{\boldsymbol{\pi}}_2 - \boldsymbol{\pi}_2)$, which depends on the sampling error in $\hat{\boldsymbol{\pi}}_2$ unless $\rho_1 = 0$. OLS estimators from (6) will be consistent for $\boldsymbol{\delta}_1, \alpha_1$, and ρ_1 .

- The OLS estimates from (6) are *control function* estimates.
- The OLS estimates of δ_1 and α_1 from (6) are *identical* to the 2SLS estimates starting from (1).
- A test of $H_0 : \rho_1 = 0$ in the equation

$$y_{i1} = \mathbf{z}_{i1}\boldsymbol{\delta}_1 + \alpha_1 y_{i2} + \rho_1 \hat{v}_{i2} + \text{error}_i$$

is the regression-based Hausman test for $H_0 : \text{Cov}(y_2, u_1) = 0$. Is easily made robust to heteroskedasticity of unknown form.

- The equivalence of IV and CF methods does not always. Add a quadratic in y_2 :

$$y_1 = \mathbf{z}_1 \boldsymbol{\delta}_1 + \alpha_1 y_2 + \gamma_1 y_2^2 + u_1 \quad (7)$$

$$E(u_1 | \mathbf{z}) = 0. \quad (8)$$

- Cannot get very far now without the stronger assumption (8).
- Let z_2 be a (nonbinary) scalar not also in \mathbf{z}_1 . Under assumption (8), we can use, say, z_2^2 as an instrument for y_2^2 . So the IVs would be $(\mathbf{z}_1, z_2, z_2^2)$ for $(\mathbf{z}_1, y_2, y_2^2)$. We could also use interactions $z_2 \mathbf{z}_1$.

- What does the CF approach entail? Because of the nonlinearity in y_2 , the CF approach is based on the conditional mean, $E(y_1|\mathbf{z}, y_2)$, rather than a linear projection.
- Therefore, we now *assume*

$$E(u_1|\mathbf{z}, y_2) = E(u_1|v_2) = \rho_1 v_2 \quad (9)$$

where

$$y_2 = \mathbf{z}\boldsymbol{\pi}_2 + v_2.$$

- Independence of (u_1, v_2) and \mathbf{z} is sufficient for the first equality. Even under the independence assumption, linearity of $E(u_1|v_2)$ is a substantive restriction.

- Under $E(u_1|\mathbf{z}, y_2) = \rho_1 v_2$, we have

$$E(y_1|\mathbf{z}, y_2) = \mathbf{z}_1 \boldsymbol{\delta}_1 + \alpha_1 y_2 + \gamma_1 y_2^2 + \rho_1 v_2. \quad (10)$$

A CF approach is immediate: replace v_2 with \hat{v}_2 and use OLS on (10).

Not equivalent to a 2SLS estimate.

- If the assumptions hold, CF likely more efficient; it is less robust than an IV approach, which requires only $E(u_1|\mathbf{z}) = 0$.
- At a minimum the CF approach requires $E(v_2|\mathbf{z}) = 0$ or $E(y_2|\mathbf{z}) = \mathbf{z}\boldsymbol{\pi}_2$, which puts serious restrictions on y_2 .

- Even in linear models with constant coefficients, CF approaches can impose extra assumptions when we base it on $E(y_1|\mathbf{z}, y_2)$, particularly when y_2 is (partially) discrete. Generally, the estimating equation is

$$E(y_1|\mathbf{z}, y_2) = \mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2 + E(u_1|\mathbf{z}, y_2). \quad (11)$$

- Suppose y_2 is binary. Generally, $E(u_1|\mathbf{z}, y_2)$ depends on the joint distribution of (u_1, y_2) given \mathbf{z} . If $y_2 = 1[\mathbf{z}\boldsymbol{\delta}_2 + e_2 \geq 0]$, (u_1, e_2) is independent of \mathbf{z} , $E(u_1|e_2) = \rho_1 e_2$, and $e_2 \sim Normal(0, 1)$, then

$$E(u_1|\mathbf{z}, y_2) = \rho_1 [y_2 \lambda(\mathbf{z}\boldsymbol{\delta}_2) - (1 - y_2) \lambda(-\mathbf{z}\boldsymbol{\delta}_2)], \quad (12)$$

where $\lambda(\cdot)$ is the inverse Mills ratio (IMR).

- The CF approach is based on

$$E(y_1|\mathbf{z}, y_2) = \mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2 + \rho_1 [y_2\lambda(\mathbf{z}\boldsymbol{\delta}_2) - (1 - y_2)\lambda(-\mathbf{z}\boldsymbol{\delta}_2)]$$

and the Heckman two-step approach (for endogeneity, not sample selection):

(i) Probit to get $\hat{\boldsymbol{\delta}}_2$ and compute $\hat{gr}_{i2} \equiv y_{i2}\lambda(\mathbf{z}_i\hat{\boldsymbol{\delta}}_2) - (1 - y_{i2})\lambda(-\mathbf{z}_i\hat{\boldsymbol{\delta}}_2)$

(generalized residual).

(ii) Regress y_{i1} on \mathbf{z}_{i1} , y_{i2} , \hat{gr}_{i2} , $i = 1, \dots, N$ (and adjust the standard errors).

- Consistency of the CF estimators hinges on the model for $D(y_2|\mathbf{z})$ being correctly specified, along with linearity in $E(u_1|e_2)$. If we just apply 2SLS directly to $y_1 = \mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1y_2 + u_1$, it makes no distinction among discrete, continuous, or some mixture for y_2 .
- How might we robustly use the binary nature of y_2 in IV estimation? Obtain the fitted probabilities, $\Phi(\mathbf{z}_i\hat{\boldsymbol{\delta}}_2)$, from the first stage probit, and then use these as IVs (not regressors!) for y_{i2} . Fully robust to misspecification of the probit model, usual standard errors from IV asymptotically valid. Efficient IV estimator if $P(y_2 = 1|\mathbf{z}) = \Phi(\mathbf{z}\boldsymbol{\delta}_2)$ and $Var(u_1|\mathbf{z}) = \sigma_1^2$.
- Similar suggestions work for y_2 a count variable or a corner solution.

2. Correlated Random Coefficient Models

- Modify the original equation as

$$y_1 = \eta_1 + \mathbf{z}_1\boldsymbol{\delta}_1 + a_1y_2 + u_1 \quad (13)$$

where a_1 , the “random coefficient” on y_2 . Heckman and Vytlačil (1998) call (13) a correlated random coefficient (CRC) model. For a random draw i , $y_{i1} = \eta_1 + \mathbf{z}_{i1}\boldsymbol{\delta}_1 + a_{i1}y_2 + u_{i1}$.

- Write $a_1 = \alpha_1 + v_1$ where $\alpha_1 = E(a_1)$ is the parameter of interest.

We can rewrite the equation as

$$y_1 = \eta_1 + \mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1y_2 + v_1y_2 + u_1 \quad (14)$$

$$\equiv \eta_1 + \mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1y_2 + e_1. \quad (15)$$

- The potential problem with applying instrumental variables is that the error term $v_1 y_2 + u_1$ is not necessarily uncorrelated with the instruments \mathbf{z} , even under

$$E(u_1|\mathbf{z}) = E(v_1|\mathbf{z}) = 0. \quad (16)$$

We want to allow y_2 and v_1 to be correlated, $Cov(v_1, y_2) \equiv \tau_1 \neq 0$. A sufficient condition that allows for any *unconditional* correlation is

$$Cov(v_1, y_2|\mathbf{z}) = Cov(v_1, y_2), \quad (17)$$

and this is sufficient for IV to consistently estimate (α_1, δ_1) .

- The usual IV estimator that ignores the randomness in a_1 is more robust than Garen's (1984) CF estimator, which adds \hat{v}_2 and $\hat{v}_2 y_2$ to the original model, or the Heckman-Vytlacil (1998) "plug-in" estimator, which replaces y_2 with $\hat{y}_2 = \mathbf{z}\hat{\pi}_2$.
- The condition $Cov(v_1, y_2 | \mathbf{z}) = Cov(v_1, y_2)$ cannot really hold for discrete y_2 . Further, Card (2001) shows how it can be violated even if y_2 is continuous. Wooldridge (2005) shows how to allow parametric heteroskedasticity.

- In the case of binary y_2 , we have what is often called the “switching regression” model. If $y_2 = 1[\mathbf{z}\boldsymbol{\delta}_2 + v_2 \geq 0]$ and $v_2|\mathbf{z} \sim \text{Normal}(0, 1)$, then

$$E(y_1|\mathbf{z}, y_2) = \eta_1 + \mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2 \\ + \rho_1 h_2(y_2, \mathbf{z}\boldsymbol{\delta}_2) + \xi_1 h_2(y_2, \mathbf{z}\boldsymbol{\delta}_2) y_2,$$

where

$$h_2(y_2, \mathbf{z}\boldsymbol{\delta}_2) = y_2 \lambda(\mathbf{z}\boldsymbol{\delta}_2) - (1 - y_2) \lambda(-\mathbf{z}\boldsymbol{\delta}_2)$$

is the generalized residual function.

- Reminder: The expression for $E(y_1|\mathbf{z}, y_2)$ is an *estimating* equation for α_1 . We do not use $E(y_1|\mathbf{z}, y_2)$, evaluated at $y_2 = 1$ and $y_2 = 0$, to obtain the treatment effect at different values of \mathbf{z} . The ATE in the model is constant and equal to α_1 .

- Common to add the interactions $y_{i2}(\mathbf{z}_{i1} - \bar{\mathbf{z}}_1)$ (same as estimating $y_2 = 0, y_2 = 1$ separately) and then α_1 remains the average treatment effect (with the sample average $\bar{\mathbf{z}}_1$ replacing $E(\mathbf{z}_1)$).
- If δ_1 is replaced with random coefficients correlated with y_2 , can interact \mathbf{z}_1 with $h_2(y_{i2}, \mathbf{z}_i \hat{\delta}_2)$ under joint normality of the random coefficients and v_2 .

- Can allow $E(v_1|v_2)$ to be more flexible [Heckman and MaCurdy (1986), Powell, Newey, and Walker (1990)].
- Also easy to allow for y_2 to follow a “heteroskedastic probit” model: replace v_2 with $e_2 = v_2/\exp(\mathbf{z}_2\boldsymbol{\gamma}_2)$ where $\exp(\mathbf{z}_2\boldsymbol{\gamma}_2) = sd(e_2|\mathbf{z})$. Estimate $\boldsymbol{\delta}_2, \boldsymbol{\gamma}_2$ by heteroskedastic probit.

3. Nonlinear Models

- Typically three approaches to nonlinear models with EEVs.
 - (1) Plug in fitted values from a first step regression (in an attempt to mimic 2SLS in linear model). More generally, try to find $E(y_1|\mathbf{z})$ or $D(y_1|\mathbf{z})$ and then impose identifying restrictions.
 - (2) CF approach: plug in residuals in an attempt to obtain $E(y_1|y_2, \mathbf{z})$ or $D(y_1|y_2, \mathbf{z})$.
 - (3) Maximum Likelihood (often limited information): Use models for $D(y_1|y_2, \mathbf{z})$ and $D(y_2|\mathbf{z})$ jointly.
- All strategies are more difficult with nonlinear models when y_2 is discrete. Some poor practices have lingered.

Binary and Fractional Responses

Probit model:

$$y_1 = 1[\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2 + u_1 \geq 0], \quad (18)$$

where $u_1|z \sim \text{Normal}(0, 1)$. Analysis goes through if we replace (\mathbf{z}_1, y_2) with any known function $\mathbf{x}_1 \equiv \mathbf{g}_1(\mathbf{z}_1, y_2)$.

- The Rivers-Vuong (1988) approach [Smith and Blundell (1986) for Tobit] is to make a homoskedastic-normal assumption on the reduced form for y_2 ,

$$y_2 = \mathbf{z}\boldsymbol{\pi}_2 + v_2, \quad v_2|\mathbf{z} \sim \text{Normal}(0, \tau_2^2). \quad (19)$$

- RV approach comes close to requiring

$$(u_1, v_2) \text{ independent of } \mathbf{z}. \quad (20)$$

If we also assume

$$(u_1, v_2) \sim \text{Bivariate Normal} \quad (21)$$

with $\rho_1 = \text{Corr}(u_1, v_2)$, then we can proceed with MLE based on $f(y_1, y_2 | \mathbf{z})$. A CF approach is available, too, based on

$$P(y_1 = 1 | \mathbf{z}, y_2) = \Phi(\mathbf{z}_1 \boldsymbol{\delta}_{\rho_1} + \alpha_{\rho_1} y_2 + \theta_{\rho_1} v_2) \quad (22)$$

where each coefficient is multiplied by $(1 - \rho_1^2)^{-1/2}$.

The RV two-step approach is

(i) OLS of y_2 on \mathbf{z} , to obtain the residuals, \hat{v}_2 .

(ii) Probit of y_1 on $\mathbf{z}_1, y_2, \hat{v}_2$ to estimate the scaled coefficients. A simple t test on \hat{v}_2 is valid to test $H_0 : \rho_1 = 0$.

• Can recover the original coefficients, which appear in the partial effects. Or,

$$\widehat{ASF}(\mathbf{z}_1, y_2) = N^{-1} \sum_{i=1}^N \Phi(\mathbf{x}_1 \hat{\boldsymbol{\beta}}_{\rho_1} + \hat{\theta}_{\rho_1} \hat{v}_{i2}), \quad (23)$$

that is, we average out the reduced form residuals, \hat{v}_{i2} . This formulation is useful for more complicated models.

- The two-step CF approach easily extends to fractional responses:

$$E(y_1|\mathbf{z}, y_2, q_1) = \Phi(\mathbf{x}_1\boldsymbol{\beta}_1 + q_1), \quad (24)$$

where \mathbf{x}_1 is a function of (\mathbf{z}_1, y_2) and q_1 contains unobservables. Can use the the *same* two-step because the Bernoulli log likelihood is in the linear exponential family. Still estimate scaled coefficients. APEs must be obtained from (23). To account for first-stage estimation, the bootstrap is convenient.

- Wooldridge (2005, Rothenberg Festschrift) describes some simple ways to make the analysis starting from (24) more flexible, including allowing $Var(q_1|y_2)$ to be heteroskedastic.

Example: Effects of school spending on student performance.

```
. sum math4 lunch rexpp found if y97
```

Variable	Obs	Mean	Std. Dev.	Min	Max
math4	1763	.6058803	.1966755	.029	1
lunch	2270	.3614616	.2535764	.0019	.9939
rexpp	2329	4261.201	789.124	1895	11779
found	2357	5895.984	1016.795	4816	10762

```
. glm math4 lrexpp lunch lenrol lrexpp94 if y97, fam(bin) link(probit) robust
note: math4 has noninteger values
```

```
Generalized linear models          No. of obs      =      1208
Optimization      : ML             Residual df    =      1203
                                          Scale parameter =          1

                                          AIC            =   .9079682
Log pseudolikelihood = -543.4128012    BIC            = -8378.243
```

math4	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
lrexpp	.2726134	.113923	2.39	0.017	.0493285	.4958983
lunch	-1.120498	.0582561	-19.23	0.000	-1.234678	-1.006318
lenrol	.0108851	.0390534	0.28	0.780	-.0656581	.0874283
lrexpp94	.1854712	.0829582	2.24	0.025	.0228761	.3480664
_cons	-3.118799	.9207049	-3.39	0.001	-4.923347	-1.31425

```
. margeff
```

```
Average partial effects after glm  
y = Pr(math4)
```

variable	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
lrexpp	.0998487	.0416701	2.40	0.017	.0181768	.1815205
lunch	-.4103988	.020199	-20.32	0.000	-.4499882	-.3708094
lenrol	.0039868	.0143069	0.28	0.781	-.0240542	.0320278
lrexpp94	.0679316	.0303795	2.24	0.025	.0083889	.1274742

```
. * Compare with OLS:
```

```
. reg math4 lrexpp lunch lenrol lrexpp94 if y97, robust
```

```
Linear regression
```

```
Number of obs = 1208  
F( 4, 1203) = 106.45  
Prob > F = 0.0000  
R-squared = 0.3114  
Root MSE = .168
```

math4	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
lrexpp	.0934219	.0415276	2.25	0.025	.0119474	.1748964
lunch	-.4205896	.0215956	-19.48	0.000	-.4629588	-.3782204
lenrol	-.0002997	.0146181	-0.02	0.984	-.0289795	.0283802
lrexpp94	.0590509	.0302958	1.95	0.052	-.0003877	.1184894
_cons	-.4838692	.3261972	-1.48	0.138	-1.123848	.1561094

```
. * Estimate the reduced form treating lrexpp as endogenous and
. * lfound as its IV:
```

```
. reg lrexpp lfound lunch lenrol lrexpp94 if y97 & e(sample)
```

Source	SS	df	MS	Number of obs = 1208	
Model	14.1288484	4	3.5322121	F(4, 1203)	= 244.58
Residual	17.3739986	1203	.014442227	Prob > F	= 0.0000
				R-squared	= 0.4485
				Adj R-squared	= 0.4467
Total	31.502847	1207	.026100122	Root MSE	= .12018

lrexpp	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
lfound	.5443139	.0302413	18.00	0.000	.4849824	.6036454
lunch	.1419003	.0135798	10.45	0.000	.1152575	.1685431
lenrol	-.0961736	.0083231	-11.55	0.000	-.112503	-.0798442
lrexpp94	.1358278	.0235749	5.76	0.000	.0895753	.1820803
_cons	3.036333	.2151718	14.11	0.000	2.614179	3.458486

```
. predict v2h, resid
(7694 missing values generated)
```

```
. glm math4 lrexpp lunch lenrol lrexpp94 v2h if y97, fam(bin) link(probit) robust
note: math4 has noninteger values
```

```
Generalized linear models           No. of obs       =       1208
Optimization      : ML              Residual df      =       1202
                                          Scale parameter =         1
Deviance          = 157.5338068      (1/df) Deviance = .1310597
Pearson          = 146.5468582      (1/df) Pearson  = .1219192

Variance function: V(u) = u*(1-u/1) [Binomial]
Link function    : g(u) = invnorm(u) [Probit]

Log pseudolikelihood = -542.6234317  AIC              = .9083169
                                          BIC              = -8372.725
```

```
-----
```

math4	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
lrexpp	.9567996	.2012636	4.75	0.000	.5623302	1.351269
lunch	-1.18315	.0585657	-20.20	0.000	-1.297937	-1.068363
lenrol	.0616713	.0399644	1.54	0.123	-.0166574	.14
lrexpp94	-.0784249	.1063432	-0.74	0.461	-.2868536	.1300039
v2h	-.8593559	.2374808	-3.62	0.000	-1.32481	-.3939021
_cons	-6.966712	1.259552	-5.53	0.000	-9.435388	-4.498036

```
-----
```

```
. * Easily reject null that spending is exogenous.
```

```
. margeff
```

```
Average partial effects after glm  
y = Pr(math4)
```

variable	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
lrexpp	.3501127	.0734569	4.77	0.000	.2061399	.4940855
lunch	-.432939	.0202452	-21.38	0.000	-.4726189	-.393259
lenrol	.0225668	.014639	1.54	0.123	-.0061252	.0512588
lrexpp94	-.0286973	.0389071	-0.74	0.461	-.1049537	.0475592
v2h	-.314455	.086817	-3.62	0.000	-.4846132	-.1442968

```
. * Standard errors need to be fixed up for two-step estimation.
```

```
. ivreg math4 lunch lenrol lrexpp94 (lrexpp = lfound) if y97, robust
```

```
Instrumental variables (2SLS) regression
```

```
Number of obs = 1208  
F( 4, 1203) = 114.28  
Prob > F = 0.0000  
R-squared = 0.2908  
Root MSE = .1705
```

math4	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
lrexpp	.3082997	.0710983	4.34	0.000	.1688093	.4477901
lunch	-.4389034	.0219076	-20.03	0.000	-.4818848	-.3959221
lenrol	.0155435	.0154313	1.01	0.314	-.0147317	.0458187
lrexpp94	-.026911	.0393419	-0.68	0.494	-.1040974	.0502754
_cons	-1.66758	.4360251	-3.82	0.000	-2.523035	-.8121261

```
Instrumented: lrexpp
```

```
Instruments: lunch lenrol lrexpp94 lfound
```

- The control function approach has some decided advantages over another two-step approach – one that appears to mimic the 2SLS estimation of the linear model.

- Consider the binary response case. Rather than conditioning on v_2 along with \mathbf{z} (and therefore y_2) to obtain

$P(y_1 = 1|z, v_2) = P(y_1 = 1|\mathbf{z}, y_2, v_2)$, we can obtain $P(y_1 = 1|\mathbf{z})$.

- To find $P(y_1 = 1|\mathbf{z})$, we plug in the reduced form for y_2 to get $y_1 = 1[\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1(\mathbf{z}\boldsymbol{\delta}_2) + \alpha_1v_2 + u_1 > 0]$. Because $\alpha_1v_2 + u_1$ is independent of \mathbf{z} and normally distributed, $P(y_1 = 1|\mathbf{z}) = \Phi\{[\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1(\mathbf{z}\boldsymbol{\delta}_2)]/\omega_1\}$. So first do OLS on the reduced form, and get fitted values, $\hat{y}_{i2} = \mathbf{z}_i\hat{\boldsymbol{\delta}}_2$. Then, probit of y_{i1} on $\mathbf{z}_{i1}, \hat{y}_{i2}$ to estimate scaled coefficients. Harder to estimate APEs and test for endogeneity.

- Danger with plugging in fitted values for y_2 is that one might be tempted to plug \hat{y}_2 into nonlinear functions, say y_2^2 or $y_2\mathbf{z}_1$. This does **not** result in consistent estimation of the scaled parameters or the partial effects. If we believe y_2 has a linear RF with additive normal error independent of \mathbf{z} , the addition of \hat{v}_2 solves the endogeneity problem regardless of how y_2 appears. Plugging in fitted values for y_2 only works in the case where the model is linear in y_2 . Plus, the CF approach makes it much easier to test the null that for endogeneity of y_2 as well as compute APEs.

- Can understand the limits of CF approach by returning to

$E(y_1|\mathbf{z}, y_2, q_1) = \Phi(\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2 + q_1)$, where y_2 is discrete.

Rivers-Vuong approach does not generally work.

- Suppose y_1 and y_2 are both binary and

$$y_2 = 1[\mathbf{z}\boldsymbol{\delta}_2 + v_2 \geq 0] \quad (25)$$

and we maintain joint normality of (u_1, v_2) . We should *not* try to mimic 2SLS as follows: (i) Do probit of y_2 on \mathbf{z} and get the fitted probabilities, $\hat{\Phi}_2 = \Phi(\mathbf{z}\hat{\boldsymbol{\delta}}_2)$. (ii) Do probit of y_1 on $\mathbf{z}_1, \hat{\Phi}_2$, that is, just replace y_2 with $\hat{\Phi}_2$.

- In general, the only strategy we have is maximum likelihood estimation based on $f(y_1|y_2, \mathbf{z})f(y_2|\mathbf{z})$. [Perhaps this is why some, such as Angrist (2001), Angrist and Pischke (2009), promote the notion of just using linear probability models estimated by 2SLS.]
- “Bivariate probit” software can be used to estimate the probit model with a binary endogenous variable.
- Parallel discussions hold for ordered probit, Tobit.

Multinomial Responses

- Recent push by Petrin and Train (2006), among others, to use control function methods where the second step estimation is something simple – such as multinomial logit, or nested logit – rather than being derived from a structural model. So, if we have reduced forms

$$\mathbf{y}_2 = \mathbf{z}\mathbf{\Pi}_2 + \mathbf{v}_2, \quad (26)$$

then we jump directly to convenient models for $P(y_1 = j | \mathbf{z}_1, \mathbf{y}_2, \mathbf{v}_2)$.

The average structural functions are obtained by averaging the response probabilities across $\hat{\mathbf{v}}_{i2}$. No convincing way to handle discrete \mathbf{y}_2 , though.

Exponential Models

- IV and CF approaches available for exponential models. Write

$$E(y_1|\mathbf{z}, y_2, r_1) = \exp(\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2 + r_1), \quad (27)$$

where r_1 is the omitted variable. As usual, CF methods based on

$$E(y_1|\mathbf{z}, y_2) = \exp(\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2)E[\exp(r_1)|\mathbf{z}, y_2].$$

For continuous y_2 , can find $E(y_1|\mathbf{z}, y_2)$ when $D(y_2|\mathbf{z})$ is homoskedastic normal (Wooldridge, 1997) and when $D(y_2|\mathbf{z})$ follows a probit (Terza, 1998). In the probit case,

$$E(y_1|\mathbf{z}, y_2) = \exp(\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2)h(y_2, \mathbf{z}\boldsymbol{\pi}_2, \theta_1)$$

$$h(y_2, \mathbf{z}\boldsymbol{\pi}_2, \theta_1) = \exp(\theta_1^2/2) \{y_2 \Phi(\theta_1 + \mathbf{z}\boldsymbol{\pi}_2)/\Phi(\mathbf{z}\boldsymbol{\pi}_2) + (1 - y_2)[1 - \Phi(\theta_1 + \mathbf{z}\boldsymbol{\pi}_2)]/[1 - \Phi(\mathbf{z}\boldsymbol{\pi}_2)]\}.$$

- IV methods that work for any \mathbf{y}_2 are available [Mullahy (1997)]. If

$$E(y_1|\mathbf{z}, \mathbf{y}_2, r_1) = \exp(\mathbf{x}_1\boldsymbol{\beta}_1 + r_1) \quad (28)$$

and r_1 is independent of \mathbf{z} then

$$E[\exp(-\mathbf{x}_1\boldsymbol{\beta}_1)y_1|\mathbf{z}] = E[\exp(r_1)|\mathbf{z}] = 1, \quad (29)$$

where $E[\exp(r_1)] = 1$ is a normalization. The moment conditions are

$$E[\exp(-\mathbf{x}_1\boldsymbol{\beta}_1)y_1 - 1|\mathbf{z}] = 0. \quad (30)$$

4. Semiparametric and Nonparametric Approaches

• Blundell and Powell (2004) show how to relax distributional assumptions on (u_1, v_2) in the model $y_1 = 1[\mathbf{x}_1\boldsymbol{\beta}_1 + u_1 > 0]$, where \mathbf{x}_1 can be any function of (\mathbf{z}_1, y_2) . Their key assumption is that y_2 can be written as $y_2 = g_2(\mathbf{z}) + v_2$, where (u_1, v_2) is independent of \mathbf{z} , which rules out discreteness in y_2 . Then

$$P(y_1 = 1|\mathbf{z}, v_2) = E(y_1|\mathbf{z}, v_2) = H(\mathbf{x}_1\boldsymbol{\beta}_1, v_2) \quad (31)$$

for some (generally unknown) function $H(\cdot, \cdot)$. The average structural function is just $ASF(\mathbf{z}_1, y_2) = E_{v_{i2}}[H(\mathbf{x}_1\boldsymbol{\beta}_1, v_{i2})]$.

- Two-step estimation: Estimate the function $g_2(\cdot)$ and then obtain residuals $\hat{v}_{i2} = y_{i2} - \hat{g}_2(\mathbf{z}_i)$. BP (2004) show how to estimate H and β_1 (up to scaled) and $G(\cdot)$, the distribution of u_1 . The ASF is obtained from $G(\mathbf{x}_1\beta_1)$ or

$$\widehat{ASF}(\mathbf{z}_1, y_2) = N^{-1} \sum_{i=1}^N \hat{H}(\mathbf{x}_1 \hat{\beta}_1, \hat{v}_{i2}); \quad (32)$$

- Blundell and Powell (2003) allow $P(y_1 = 1|\mathbf{z}, y_2)$ to have general form $H(\mathbf{z}_1, y_2, v_2)$, and the second-step estimation is entirely nonparametric. Further, $\hat{g}_2(\cdot)$ can be fully nonparametric. Parametric approximations might produce good estimates of the APEs.

- BP (2003) consider a very general setup: $y_1 = g_1(\mathbf{z}_1, \mathbf{y}_2, u_1)$, with

$$ASF_1(\mathbf{z}_1, \mathbf{y}_2) = \int g_1(\mathbf{z}_1, \mathbf{y}_2, u_1) dF_1(u_1), \quad (33)$$

where F_1 is the distribution of u_1 . Key restrictions are that \mathbf{y}_2 can be written as

$$\mathbf{y}_2 = \mathbf{g}_2(\mathbf{z}) + \mathbf{v}_2, \quad (34)$$

where (u_1, \mathbf{v}_2) is independent of \mathbf{z} .

- Key: ASF can be obtained from $E(y_1|\mathbf{z}_1, \mathbf{y}_2, \mathbf{v}_2) = h_1(\mathbf{z}_1, \mathbf{y}_2, \mathbf{v}_2)$ by averaging out \mathbf{v}_2 , and fully nonparametric two-step estimates are available.
- The focus on the ASF is liberating. It justifies flexible parametric approaches that need not be tied to “structural” equations. In particular, we can just skip modeling $g_1(\cdot)$ and start with $E(y_1|\mathbf{z}_1, \mathbf{y}_2, \mathbf{v}_2)$.
- For example, if y_1 is binary or a fraction and y_2 is a scalar,

$$E(y_1|\mathbf{z}_1, y_2, v_2) = \Phi(\mathbf{z}_1\boldsymbol{\delta}_1 + \alpha_1 y_2 + \rho_1 v_2 + \eta_1 v_2^2 + \mathbf{z}_1 v_2 \boldsymbol{\xi}_1 + \omega_1 y_2 v_2 + \dots)$$

5. Methods for Panel Data

- Combine methods for correlated random effects models with CF methods for nonlinear panel data models with unobserved heterogeneity and EEVs.
- Illustrate a parametric approach used by Papke and Wooldridge (2008), which applies to binary and fractional responses.
- Nothing appears to be known about applying “fixed effects” probit to estimate the fixed effects while also dealing with endogeneity. Likely to be poor for small T .

- Model with time-constant unobserved heterogeneity, c_{i1} , and time-varying unobservables, v_{it1} , as

$$E(y_{it1}|y_{it2}, \mathbf{z}_i, c_{i1}, v_{it1}) = \Phi(\alpha_1 y_{it2} + \mathbf{z}_{it1} \boldsymbol{\delta}_1 + c_{i1} + v_{it1}). \quad (35)$$

Allow the heterogeneity, c_{i1} , to be correlated with y_{it2} and \mathbf{z}_i , where $\mathbf{z}_i = (\mathbf{z}_{i1}, \dots, \mathbf{z}_{iT})$ is the vector of strictly exogenous variables (conditional on c_{i1}). The time-varying omitted variable, v_{it1} , is uncorrelated with \mathbf{z}_i – strict exogeneity – but may be correlated with y_{it2} . As an example, y_{it1} is a female labor force participation indicator and y_{it2} is other sources of income.

- Write $\mathbf{z}_{it} = (\mathbf{z}_{it1}, \mathbf{z}_{it2})$, so that the time-varying IVs \mathbf{z}_{it2} are excluded from the “structural.”
- Chamberlain approach:

$$c_{i1} = \psi_1 + \bar{\mathbf{z}}_i \boldsymbol{\xi}_1 + a_{i1}, a_{i1} | \mathbf{z}_i \sim \text{Normal}(0, \sigma_{a_1}^2). \quad (36)$$

Next step:

$$E(y_{it1} | y_{it2}, \mathbf{z}_i, r_{it1}) = \Phi(\alpha_1 y_{it2} + \mathbf{z}_{it1} \boldsymbol{\delta}_1 + \psi_1 + \bar{\mathbf{z}}_i \boldsymbol{\xi}_1 + r_{it1})$$

where $r_{it1} = a_{i1} + v_{it1}$. Next, assume a linear reduced form for y_{it2} :

$$y_{it2} = \psi_2 + \mathbf{z}_{it} \boldsymbol{\delta}_2 + \bar{\mathbf{z}}_i \boldsymbol{\xi}_2 + v_{it2}, t = 1, \dots, T. \quad (37)$$

- Rules out discrete y_{it2} because

$$r_{it1} = \eta_1 v_{it2} + e_{it1}, \quad (38)$$

$$e_{it1} | (\mathbf{z}_i, v_{it2}) \sim \text{Normal}(0, \sigma_{e_1}^2), t = 1, \dots, T. \quad (39)$$

Then

$$\begin{aligned} E(y_{it1} | \mathbf{z}_i, y_{it2}, v_{it2}) = & \Phi(\alpha_{e1} y_{it2} + \mathbf{z}_{it1} \boldsymbol{\delta}_{e1} \\ & + \psi_{e1} + \bar{\mathbf{z}}_i \boldsymbol{\xi}_{e1} + \eta_{e1} v_{it2}) \end{aligned} \quad (40)$$

where the “e” subscript denotes division by $(1 + \sigma_{e_1}^2)^{1/2}$. This equation is the basis for CF estimation.

- Simple two-step procedure: (i) Estimate the reduced form for y_{it2} (pooled across t , or maybe for each t separately; at a minimum, different time period intercepts should be allowed). Obtain the residuals, \hat{v}_{it2} for all (i, t) pairs. The estimate of δ_2 is the fixed effects estimate. (ii) Use the pooled probit (quasi)-MLE of y_{it1} on $y_{it2}, \mathbf{z}_{it1}, \bar{\mathbf{z}}_i, \hat{v}_{it2}$ to estimate $\alpha_{e1}, \delta_{e1}, \psi_{e1}, \xi_{e1}$ and η_{e1} .
- Delta method or bootstrapping (resampling cross section units) for standard errors. Can ignore first-stage estimation to test $\eta_{e1} = 0$ (but test should be fully robust to variance misspecification and serial independence).

- Estimates of average partial effects are based on the average structural function,

$$E_{(c_{i1}, v_{it1})} [\Phi(\alpha_1 y_{t2} + \mathbf{z}_{t1} \boldsymbol{\delta}_1 + c_{i1} + v_{it1})], \quad (41)$$

which is consistently estimated as

$$N^{-1} \sum_{i=1}^N \Phi(\hat{\alpha}_{e1} y_{t2} + \mathbf{z}_{t1} \hat{\boldsymbol{\delta}}_{e1} + \hat{\psi}_{e1} + \bar{\mathbf{z}}_i \hat{\boldsymbol{\xi}}_{e1} + \hat{\eta}_{e1} \hat{v}_{it2}). \quad (42)$$

These APEs, typically with further averaging out across t and perhaps over y_{t2} and \mathbf{z}_{t1} , can be compared directly with fixed effects IV estimates.

EXAMPLE: Effects of Spending on Test Pass Rates

- Reform occurs between 1993/94 and 1994/95 school year; its passage was a surprise to almost everyone.
- Since 1994/95, each district receives a foundation allowance, based on revenues in 1993/94.
- Initially, all districts were brought up to a minimum allowance – \$4,200 in the first year. The goal was to eventually give each district a basic allowance (\$5,000 in the first year).
- Districts divided into three groups in 1994/95 for purposes of initial foundation allowance. Subsequent grants determined by statewide School Aid Fund.

- Catch-up formula for districts receiving below the basic. Initially, more than half of the districts received less than the basic allowance. By 1998/99, it was down to about 36%. In 1999/00, all districts began receiving the basic allowance, which was then \$5,700. Two-thirds of all districts now receive the basic allowance.
- From 1991/92 to 2003/04, in the 10th percentile, expenditures rose from \$4,616 (2004 dollars) to \$7,125, a 54 percent increase. In the 50th percentile, it was a 48 percent increase. In the 90th percentile, per pupil expenditures rose from \$7,132 in 1992/93 to \$9,529, a 34 percent increase.

- Response variable: $math4$, the fraction of fourth graders passing the MEAP math test at a school.
- Spending variable is $\log(avgrexppp)$, where the average is over the current and previous three years.
- The linear model is

$$math4_{it} = \theta_t + \beta_1 \log(avgrexpp_{it}) + \beta_2 lunch_{it} + \beta_3 \log(enroll_{it}) + c_{i1} + u_{it1}$$

Estimating this model by fixed effects is identical to adding the time averages of the three explanatory variables and using pooled OLS.

- The “fractional probit” model:

$$E(math4_{it} | \mathbf{x}_{i1}, \mathbf{x}_{i2}, \dots, \mathbf{x}_{iT}) = \Phi(\theta_{at} + \mathbf{x}_{it} \boldsymbol{\beta}_a + \bar{\mathbf{x}}_i \boldsymbol{\xi}_a).$$

- Allowing spending to be endogenous. Controlling for 1993/94 spending, foundation grant should be exogenous. Exploit nonsmoothness in the grant as a function of initial spending.

$$\begin{aligned} \mathit{math4}_{it} = & \theta_t + \beta_1 \log(\mathit{avgrexp}_{it}) + \beta_2 \mathit{lunch}_{it} + \beta_3 \log(\mathit{enroll}_{it}) \\ & + \beta_{4t} \log(\mathit{rexp}_{i,1994}) + \xi_1 \overline{\mathit{lunch}_i} + \xi_2 \overline{\log(\mathit{enroll}_i)} + v_{it1} \end{aligned}$$

- And, fractional probit version of this.

```

. use meap92_01

. xtset distid year
    panel variable:  distid (strongly balanced)
    time variable:   year, 1992 to 2001
                   delta: 1 unit

. des math4 avgrexp lunch enroll found

```

variable name	storage type	display format	value label	variable label
math4	double	%9.0g		fraction satisfactory, 4th grade math
avgrexp	float	%9.0g		(rexppp + rexppp_1 + rexppp_2 + rexppp_3)/4
lunch	float	%9.0g		fraction eligible for free lunch
enroll	float	%9.0g		district enrollment
found	int	%9.0g		foundation grant, \$: 1995-2001

```

. sum math4 rexppp lunch

```

Variable	Obs	Mean	Std. Dev.	Min	Max
math4	5010	.6149834	.1912023	.059	1
rexppp	5010	6331.99	1168.198	3553.361	15191.49
lunch	5010	.2802852	.1571325	.0087	.9126999

```
. xtreg math4 lavgrexp lunch lenroll y96-y01, fe cluster(distid)
```

```
Fixed-effects (within) regression      Number of obs      =      3507
Group variable: distid                 Number of groups   =       501
```

```
R-sq:  within  = 0.4713                Obs per group: min =       7
        between = 0.0219                avg   =      7.0
        overall = 0.2049                max   =       7
```

```
corr(u_i, Xb) = -0.1787                F(9,500)          =     171.93
                                                Prob > F          =      0.0000
```

(Std. Err. adjusted for 501 clusters in distid)

math4	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
lavgrexp	.3770929	.0705668	5.34	0.000	.2384489	.5157369
lunch	-.0419467	.0731611	-0.57	0.567	-.1856877	.1017944
lenroll	.0020568	.0488107	0.04	0.966	-.0938426	.0979561
y96	-.0155968	.0063937	-2.44	0.015	-.0281587	-.003035
y97	-.0589732	.0095232	-6.19	0.000	-.0776837	-.0402628
y98	.0781686	.0112949	6.92	0.000	.0559772	.1003599
y99	.0642748	.0123103	5.22	0.000	.0400884	.0884612
y00	.0895688	.0133223	6.72	0.000	.0633942	.1157434
y01	.0630091	.014717	4.28	0.000	.0340943	.0919239
_cons	-2.640402	.8161357	-3.24	0.001	-4.24388	-1.036924

```

-----+-----
sigma_u | .1130256
sigma_e | .08314135
rho     | .64888558 (fraction of variance due to u_i)
-----

```

```
. des alavgrexp alunch alenroll
```

variable name	storage type	display format	value label	variable label
alavgrexp	float	%9.0g		time average lavgrexp, 1995-2001
alunch	float	%9.0g		time average lunch, 1995-2001
alenroll	float	%9.0g		time average lenroll, 1995-2001


```
. reg math4 lavgrexp alavgrexp lunch alunch lenroll alenroll y96-y01,
    cluster(distid)
```

Linear regression

```
Number of obs =    3507
F( 12,    500) =  161.09
Prob > F      =   0.0000
R-squared     =   0.4218
Root MSE     =   .11542
```

(Std. Err. adjusted for 501 clusters in distid)

math4	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
lavgrexp	.377092	.0705971	5.34	0.000	.2383884	.5157956
alavgrexp	-.286541	.0731797	-3.92	0.000	-.4303185	-.1427635
lunch	-.0419466	.0731925	-0.57	0.567	-.1857494	.1018562
alunch	-.3770088	.0766141	-4.92	0.000	-.5275341	-.2264835
lenroll	.0020566	.0488317	0.04	0.966	-.093884	.0979972
alenroll	-.0031646	.0491534	-0.06	0.949	-.0997373	.0934082
y96	-.0155968	.0063965	-2.44	0.015	-.0281641	-.0030295
y97	-.0589731	.0095273	-6.19	0.000	-.0776916	-.0402546
y98	.0781687	.0112998	6.92	0.000	.0559678	.1003696
y99	.064275	.0123156	5.22	0.000	.0400782	.0884717
y00	.089569	.013328	6.72	0.000	.0633831	.1157548
y01	.0630093	.0147233	4.28	0.000	.0340821	.0919365
_cons	-.0006233	.2450239	-0.00	0.998	-.4820268	.4807801

. * Now use fractional probit.

. glm math4 lavgrexp alavgrexp lunch alunch lenroll alenroll y96-y01,
fa(bin) link(probit) cluster(distid)
note: math4 has non-integer values

Generalized linear models		No. of obs	=	3507
Optimization	: ML	Residual df	=	3494
		Scale parameter	=	1
Deviance	=	237.643665	(1/df) Deviance	= .0680148
Pearson	=	225.1094075	(1/df) Pearson	= .0644274

(Std. Err. adjusted for 501 clusters in distid)

math4	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
lavgrexp	.8810302	.2068026	4.26	0.000	.4757045	1.286356
alavgrexp	-.5814474	.2229411	-2.61	0.009	-1.018404	-.1444909
lunch	-.2189714	.2071544	-1.06	0.290	-.6249865	.1870437
alunch	-.9966635	.2155739	-4.62	0.000	-1.419181	-.5741465
lenroll	.0887804	.1382077	0.64	0.521	-.1821017	.3596626
alenroll	-.0893612	.1387674	-0.64	0.520	-.3613404	.1826181
y96	-.0362309	.0178481	-2.03	0.042	-.0712125	-.0012493
y97	-.1467327	.0273205	-5.37	0.000	-.20028	-.0931855
y98	.2520084	.0337706	7.46	0.000	.1858192	.3181975
y99	.2152507	.0367226	5.86	0.000	.1432757	.2872257
y00	.3049632	.0399409	7.64	0.000	.2266805	.3832459
y01	.2257321	.0439608	5.13	0.000	.1395705	.3118938
_cons	-1.855832	.7556621	-2.46	0.014	-3.336902	-.3747616

. margeff

Average partial effects after glm
y = Pr(math4)

variable	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
lavgrexp	.2968496	.0695326	4.27	0.000	.1605682	.433131
alavgrexp	-.1959097	.0750686	-2.61	0.009	-.3430414	-.0487781
lunch	-.0737791	.0698318	-1.06	0.291	-.2106469	.0630887
alunch	-.3358104	.0723725	-4.64	0.000	-.4776579	-.1939629
lenroll	.0299132	.0465622	0.64	0.521	-.061347	.1211734
alenroll	-.0301089	.0467477	-0.64	0.520	-.1217326	.0615149
y96	-.0122924	.0061107	-2.01	0.044	-.0242692	-.0003156
y97	-.0508008	.0097646	-5.20	0.000	-.069939	-.0316625
y98	.0809879	.0100272	8.08	0.000	.0613349	.1006408
y99	.0696954	.0111375	6.26	0.000	.0478662	.0915245
y00	.0970224	.0115066	8.43	0.000	.0744698	.119575
y01	.0729829	.0132849	5.49	0.000	.046945	.0990208

. * These standard errors are very close to bootstrapped standard errors.

```
. xtgee math4 lavgrexp alavgrexp lunch alunch lenroll alenroll y96-y01,
    fa(bin) link(probit) corr(exch) robust
```

```
GEE population-averaged model
Group variable:          distid      Number of obs      =      3507
Link:                   probit       Number of groups   =      501
Family:                 binomial     Obs per group: min =      7
Correlation:           exchangeable  avg               =     7.0
Scale parameter:       1             max               =      7
                                Wald chi2(12)      =    1815.43
                                Prob > chi2         =      0.0000
```

(Std. Err. adjusted for clustering on distid)

math4	Coef.	Semi-robust Std. Err.	z	P> z	[95% Conf. Interval]	
lavgrexp	.884564	.2060662	4.29	0.000	.4806817	1.288446
alavgrexp	-.5835138	.2236705	-2.61	0.009	-1.0219	-.1451277
lunch	-.2372942	.2091221	-1.13	0.256	-.6471659	.1725775
alunch	-.9754696	.2170624	-4.49	0.000	-1.400904	-.5500351
lenroll	.0875629	.1387427	0.63	0.528	-.1843677	.3594935
alenroll	-.0820307	.1393712	-0.59	0.556	-.3551933	.1911318
y96	-.0364771	.0178529	-2.04	0.041	-.0714681	-.001486
y97	-.1471389	.0273264	-5.38	0.000	-.2006976	-.0935801
y98	.2515377	.0337018	7.46	0.000	.1854833	.317592
y99	.2148552	.0366599	5.86	0.000	.143003	.2867073
y00	.3046286	.0399143	7.63	0.000	.2263981	.3828591
y01	.2256619	.0438877	5.14	0.000	.1396437	.3116801
_cons	-1.914975	.7528262	-2.54	0.011	-3.390487	-.4394628

. margeff

Average partial effects after xtgee

y = Pr(math4)

variable	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
lavgrexp	.2979576	.0692519	4.30	0.000	.1622263	.4336889
alavgrexp	-.1965515	.0752801	-2.61	0.009	-.3440978	-.0490052
lunch	-.0799305	.0704803	-1.13	0.257	-.2180693	.0582082
alunch	-.3285784	.0728656	-4.51	0.000	-.4713924	-.1857644
lenroll	.0294948	.0467283	0.63	0.528	-.0620909	.1210805
alenroll	-.0276313	.0469381	-0.59	0.556	-.1196283	.0643656
y96	-.012373	.0061106	-2.02	0.043	-.0243497	-.0003964
y97	-.0509306	.0097618	-5.22	0.000	-.0700633	-.0317979
y98	.0808226	.010009	8.08	0.000	.0612054	.1004399
y99	.0695541	.0111192	6.26	0.000	.0477609	.0913472
y00	.0968972	.0115004	8.43	0.000	.0743568	.1194376
y01	.0729416	.0132624	5.50	0.000	.0469478	.0989353

```

. * Now allow spending to be endogenous. Use foundation allowance, and
. * interactions, as IVs.
. * First, linear model:

. ivreg math4 lunch alunch lenroll alenroll y96-y01 lexppp94 le94y96-le94y01
  (lavgrexp = lfound lfndy96-lfndy01), cluster(distid)

```

```

Instrumental variables (2SLS) regression
Number of obs =      3507
F( 18,    500) =   107.05
Prob > F      =    0.0000
R-squared     =    0.4134
Root MSE     =    .11635

```

(Std. Err. adjusted for 501 clusters in distid)

math4	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
lavgrexp	.5545247	.2205466	2.51	0.012	.1212123	.987837
lunch	-.0621991	.0742948	-0.84	0.403	-.2081675	.0837693
alunch	-.4207815	.0758344	-5.55	0.000	-.5697749	-.2717882
lenroll	.0463616	.0696215	0.67	0.506	-.0904253	.1831484
alenroll	-.049052	.070249	-0.70	0.485	-.1870716	.0889676
y96	-1.085453	.2736479	-3.97	0.000	-1.623095	-.5478119
y97	-1.049922	.376541	-2.79	0.005	-1.78972	-.3101244
y98	-.4548311	.4958826	-0.92	0.359	-1.429102	.5194394
y99	-.4360973	.5893671	-0.74	0.460	-1.594038	.7218439
y00	-.3559283	.6509999	-0.55	0.585	-1.634961	.923104
y01	-.704579	.7310773	-0.96	0.336	-2.140941	.7317831
lexppp94	-.4343213	.2189488	-1.98	0.048	-.8644944	-.0041482
le94y96	.1253255	.0318181	3.94	0.000	.0628119	.1878392
le94y97	.11487	.0425422	2.70	0.007	.0312865	.1984534
le94y98	.0599439	.0554377	1.08	0.280	-.0489757	.1688636
le94y99	.0557854	.0661784	0.84	0.400	-.0742367	.1858075
le94y00	.048899	.0727172	0.67	0.502	-.0939699	.1917678

le94y01		.0865874	.0816732	1.06	0.290	-.0738776	.2470524
_cons		-.334823	.2593105	-1.29	0.197	-.8442955	.1746496

Instrumented: lavgrexp
Instruments: lunch alunch lenroll alenroll y96 y97 y98 y99 y00 y01
lexppp94 le94y96 le94y97 le94y98 le94y99 le94y00 le94y01
lfound lfndy96 lfndy97 lfndy98 lfndy99 lfndy00 lfndy01

. * Estimate is substantially larger than when spending is treated as exogenous.

```
. * Get reduced form residuals for fractional probit:
```

```
. reg lavgrexp lfound lfndy96-lfndy01 lunch alunch lenroll alenroll y96-y01  
lexppp94 le94y96-le94y01, cluster(distid)
```

Linear regression

```
Number of obs = 3507  
F( 24, 500) = 1174.57  
Prob > F = 0.0000  
R-squared = 0.9327  
Root MSE = .03987
```

(Std. Err. adjusted for 501 clusters in distid)

lavgrexp	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
lfound	.2447063	.0417034	5.87	0.000	.1627709	.3266417
lfndy96	.0053951	.0254713	0.21	0.832	-.044649	.0554391
lfndy97	-.0059551	.0401705	-0.15	0.882	-.0848789	.0729687
lfndy98	.0045356	.0510673	0.09	0.929	-.0957972	.1048685
lfndy99	.0920788	.0493854	1.86	0.063	-.0049497	.1891074
lfndy00	.1364484	.0490355	2.78	0.006	.0401074	.2327894
lfndy01	.2364039	.0555885	4.25	0.000	.127188	.3456198
...						
_cons	.1632959	.0996687	1.64	0.102	-.0325251	.359117

```
. predict v2hat, resid  
(1503 missing values generated)
```



```
. glm math4 lavgrexp v2hat lunch alunch lenroll alenroll y96-y01 lexppp94
    le94y96-le94y01, fa(bin) link(probit) cluster(distid)
note: math4 has non-integer values
```

```
Generalized linear models          No. of obs      =       3507
Optimization      : ML              Residual df    =       3487
                                          Scale parameter =         1
Deviance          = 236.0659249      (1/df) Deviance = .0676989
Pearson          = 223.3709371      (1/df) Pearson  = .0640582
```

```
Variance function: V(u) = u*(1-u/1)      [Binomial]
Link function     : g(u) = invnorm(u)    [Probit]
```

(Std. Err. adjusted for 501 clusters in distid)

math4	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
lavgrexp	1.731039	.6541194	2.65	0.008	.4489886	3.013089
v2hat	-1.378126	.720843	-1.91	0.056	-2.790952	.0347007
lunch	-.2980214	.2125498	-1.40	0.161	-.7146114	.1185686
alunch	-1.114775	.2188037	-5.09	0.000	-1.543623	-.685928
lenroll	.2856761	.197511	1.45	0.148	-.1014383	.6727905
alenroll	-.2909903	.1988745	-1.46	0.143	-.6807771	.0987966
...						
_cons	-2.455592	.7329693	-3.35	0.001	-3.892185	-1.018998

```
. margeff
```

```
Average partial effects after glm
```

```
y = Pr(math4)
```

```
-----
```

variable	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
lavgrexp	.5830163	.2203345	2.65	0.008	.1511686	1.014864
v2hat	-.4641533	.242971	-1.91	0.056	-.9403678	.0120611
lunch	-.1003741	.0716361	-1.40	0.161	-.2407782	.04003
alunch	-.3754579	.0734083	-5.11	0.000	-.5193355	-.2315803
lenroll	.0962161	.0665257	1.45	0.148	-.0341719	.2266041
alenroll	-.0980059	.0669786	-1.46	0.143	-.2292817	.0332698
...						

```
-----
```

- . * These standard errors do not account for the first-stage estimation. Should
- . * use the panel bootstrap accounting for both stages.
- . * Only marginal evidence that spending is endogenous, but the negative sign
- . * fits the story that districts increase spending when performance is
- . * (expected to be) worse, based on unobservables (to us).

Model:	Linear	Fractional Probit	
Estimation Method:	Instrumental Variables	Pooled QMLE	
	Coefficient	Coefficient	APE
$\log(\text{arexppp})$.555	1.731	.583
	(.221)	(.759)	(.255)
lunch	-.062	-.298	-.100
	(.074)	(.202)	(.068)
$\log(\text{enroll})$.046	.286	.096
	(.070)	(.209)	(.070)
\hat{v}_2	-.424	-1.378	—
	(.232)	(.811)	—
Scale Factor	—	.337	